

Applications of high-resolution aerial imagery and a small unmanned aircraft system in Everglades science



Matthew A. Burgess

C.L. Zweig, S. Newman, M.I. Cook, H.L. Rodgers, R.R. Carthy,
B.E. Wilkinson, T.J. Whitley, T.S. Ward, J.G. DiRodio, P.C. Frederick,
P.G. Ifju, S.E. Smith, and H.F. Percival



Acronyms and Terminology

UA, UAS, or RPV = Unmanned Aircraft, or Unmanned Aerial Vehicle, Remotely Piloted Vehicle:

-Strictly the physical flying component of a remotely flown aircraft

UAS, or RPAS = Unmanned Aircraft System, or Remotely Piloted Aircraft System:

-The physical flying component +

-The manned ground control station +

-The uplink/downlink communications between them

Drone:

-A stingless male bee that mates with the queen

-A continuous, low, dull, humming sound

-A pilotless 'dumb' object used for combat target practice

-A term that applies to UASs of the shooting military

-'A deadly flying robot raining terror'

-'A pilotless flying robot used for spying'



Brief Overview of the UFUASRP

- In our 15th year of existence
- Natural resource-based applications from the very beginning
- Approach from the natural resource scientist point of view; simplicity of use and budget
- Over last seven years, interest in sUAS for natural resources has grown exponentially
- Truly interdisciplinary research program
- As of April 17, 2015, we have 14 active FAA Certificates of Authorization; three additional pending



Airframe/Payload Considerations

- What is your *SCIENTIFIC QUESTION*? Define your target!
- What is your desired *END PRODUCT*? Individual images (samples), a mosaic (contiguous map or layer), a video (documentation of behavior), etc.
- What *KINDS OF DATA* do you need to collect to produce your end product? Identify the sensors that can deliver those data.



Airframe/Payload Considerations

- Based on your sensor or sensor suite, select a *SUITABLE AIRFRAME* as a platform for your sensors. Capacity, runtime, sound, area, etc.
- What is your plan to collect *SCIENTIFICALLY SIGNIFICANT DATA*? Consult your statistician before you head out into the field!
- What is your plan for *POST-PROCESSING* the data collected? Do it yourself, contract it out to an expert, have a student do it, etc.
- What do you intend to do about *ARCHIVING* the data? File sizes are getting bigger...

Airframe Considerations



1) Design

- Fixed-wing
- Rotor-wing



2) Power Source

- Liquid (wet) fuel
- Battery



3) Physical Size

- Micro UAS
- Large UAS



4) Operating Environment

- Terrain
- Temperature

UFUASRP Airframe Evolution



MLB Fold Bat
(2002-3)



UF Tadpole
(2004-5)



UF Polaris/Nova
(2006-8)



UF Nova 2
(2008-9)

UF Nova 2.1 sUAS



-9 ft. wingspan
-14 lbs. fully loaded



-Hand launchable
-Built in-house



-Amphibious
-65 min. runtime



DJI Spreading Wings S1000+ Octocopter Rotor-wing sUAS



-3.5 ft. diameter
-10→24 lbs. takeoff



-Portable
-Off-the-Shelf



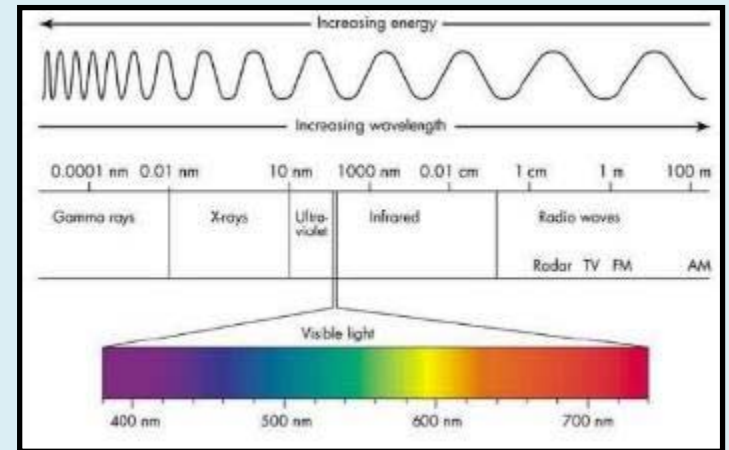
-Autonomous
-25 min. runtime



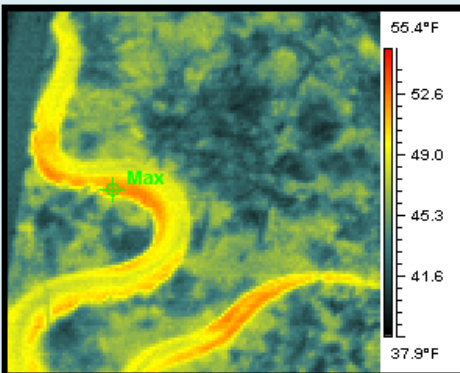
Payload Considerations



- 1) RGB and NIR
 - Resolution
 - Triggering



- 2) Multispectral and Hyperspectral
 - Spectral Range
 - Triggering
 - Cost



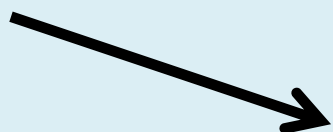
- 3) Thermal
 - Resolution
 - Georeferencing
 - Cost



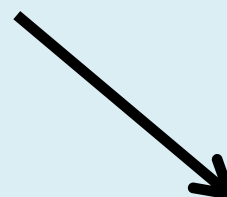
UFUASRP Optical Payloads – Evolution



Canon Elura 2 MC



Canon PowerShot A640



Olympus E-420

Optical Sensor RGB and NIR – Evolution



Olympus E-420



Canon EOS 2Ti



Sony A7R



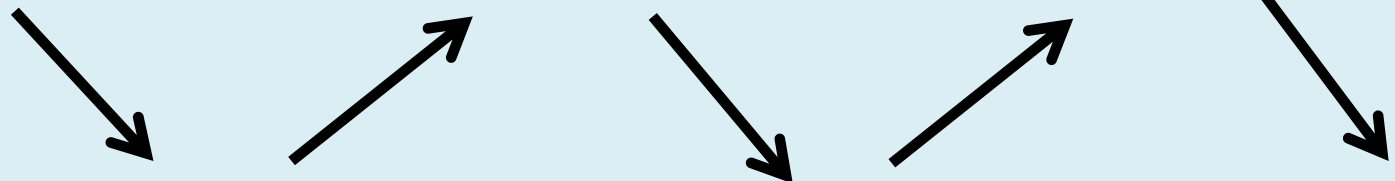
Canon EOS-M



Sony A6000



Canon EOS SL1



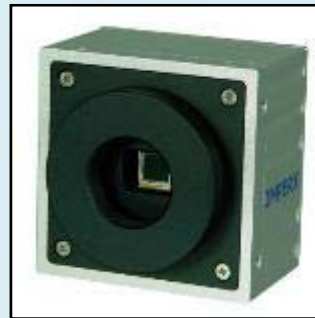
Optical Sensor—Thermal, Multispectral and Hyperspectral, and HD Video



FLIR Photon
Thermal



FLIR A65 SC
Thermal



Imperx B6640
Multispectral



Rikola
Hyperspectral



GoPro Hero 3



GoPro Hero 4

Authorizations/Regulations/Approvals

www.faa.gov/uas
www.modelaircraft.org
www.auvsi.org

-Certificate of Authorization

-Aircraft Airworthiness

-Crew Certification

-Local Permission

-Notice to Airmen

-Flight Restrictions

-Failsafe Approvals

-Institutional Rules

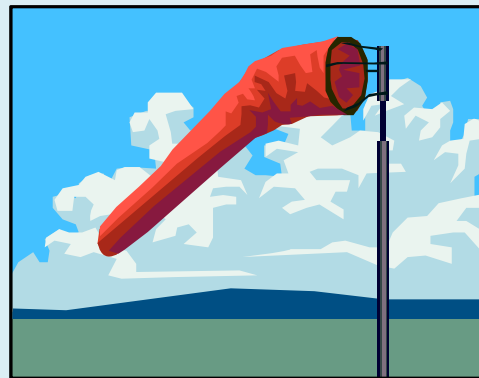
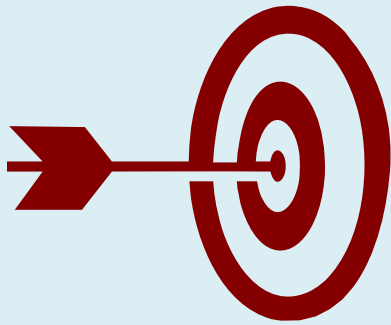
-International Traffic in Arms Regulations (ITAR)

-Export Administration Regulations (EAR)

» United States Munitions List; Commerce Control List



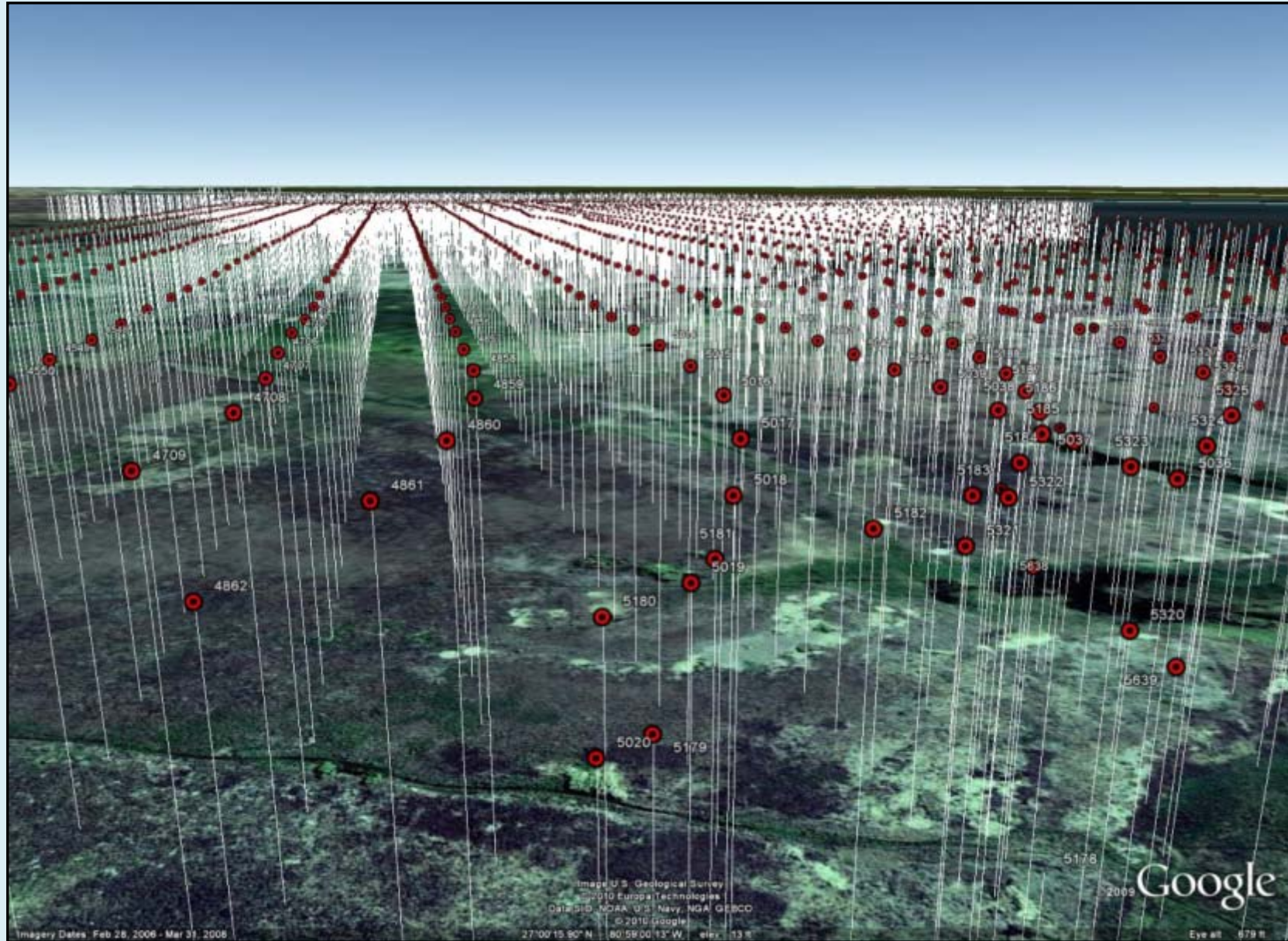
The Flight Planning Process



Flight Planning: Who, Where, and When?



Flight Planning: Complete Coverage



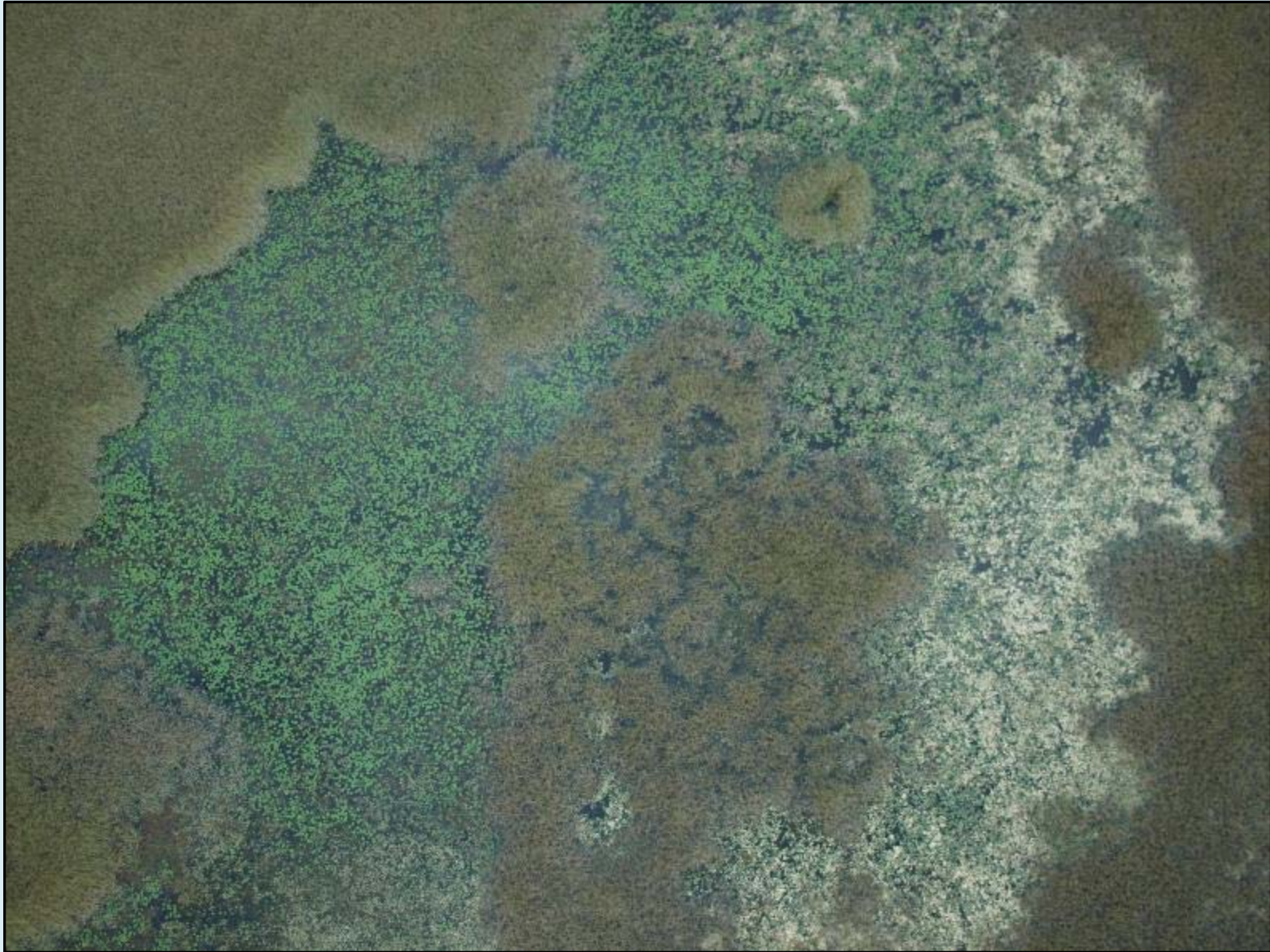
Wetland Vegetation Classification



Wetland Vegetation Classification



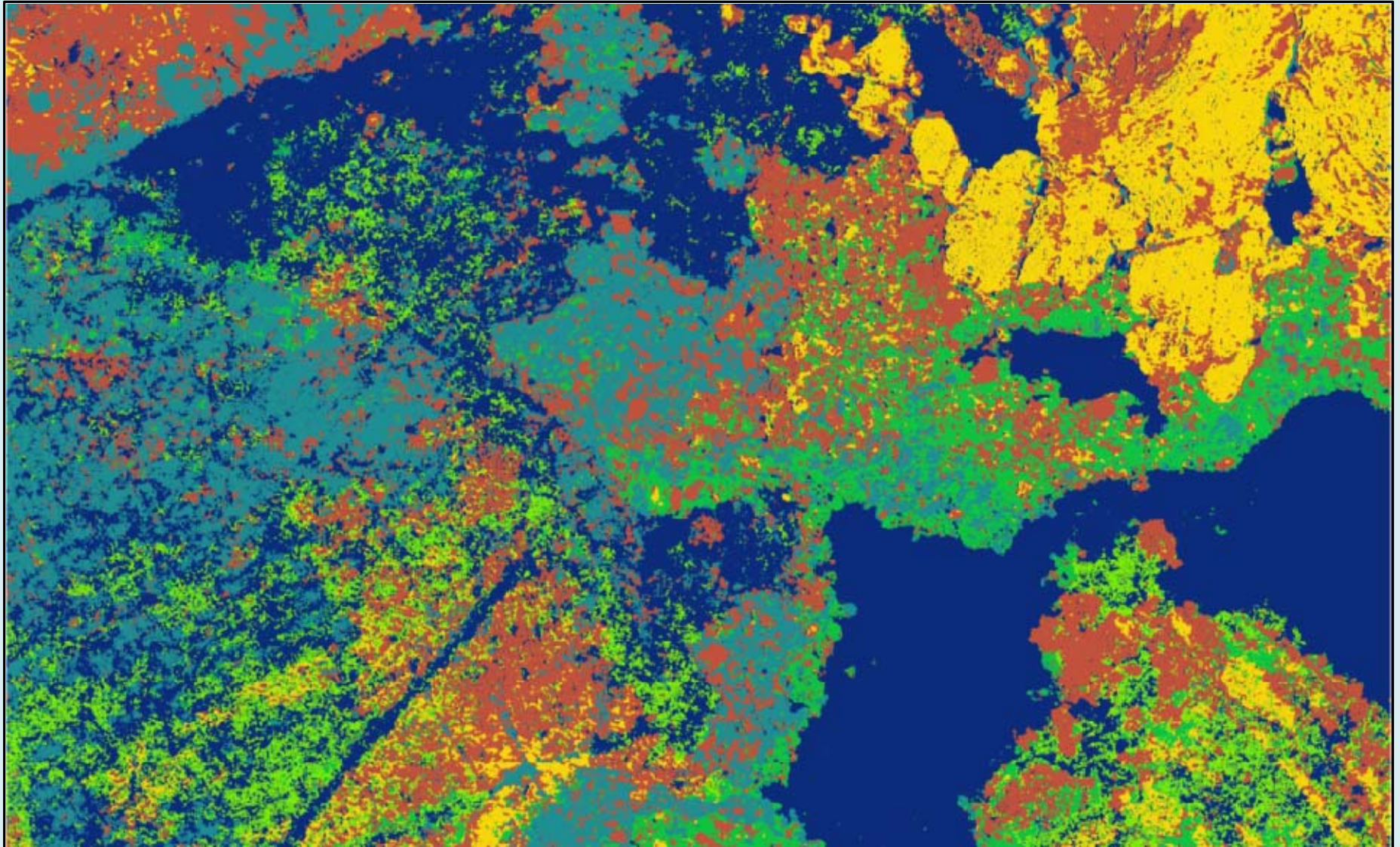
Wetland Vegetation Classification



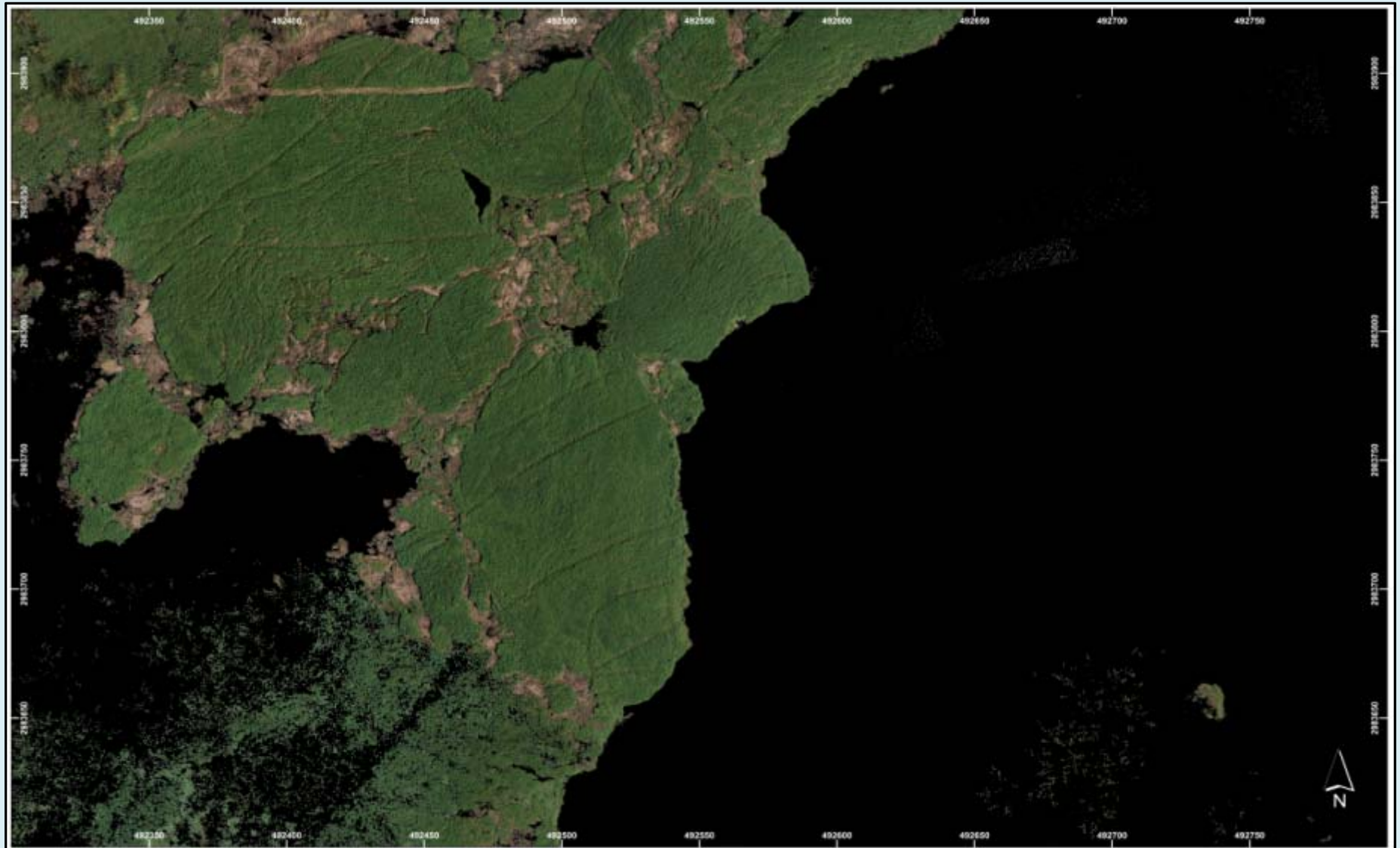
Veg. Pre-treatment Mosaic



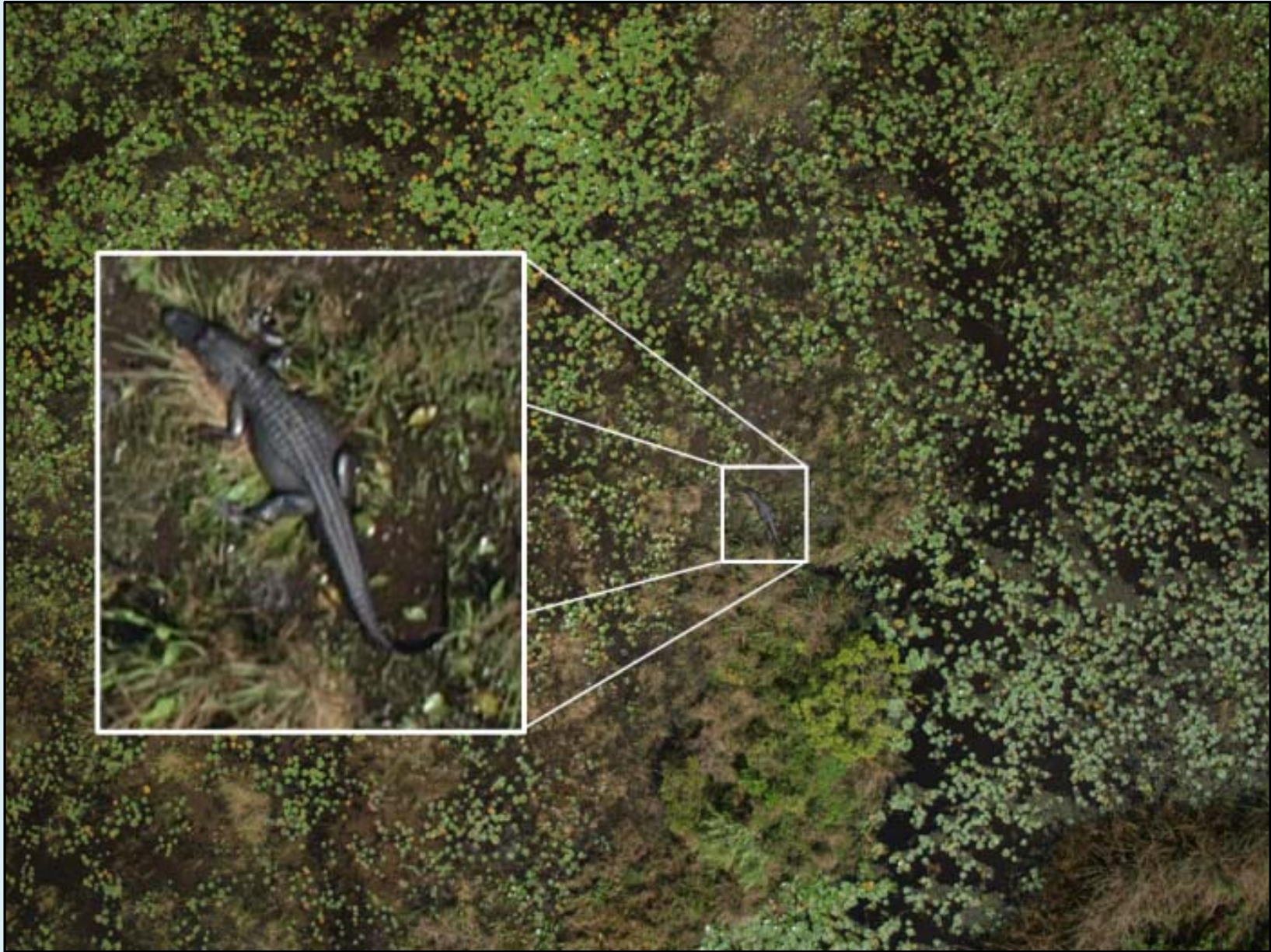
Veg. Classified Mosaic



Veg. Post-treatment Mosaic



Aerial Advantages



Nesting Wading Bird Colony Assessments



Nesting Wading Bird Colony Assessments



Infrastructure Monitoring



UFUASRP Multispectral Mosaics

Picayune Strand State Forest

Invasive Vegetation Site

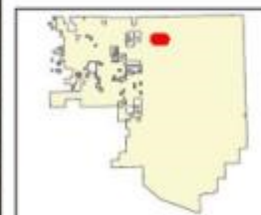
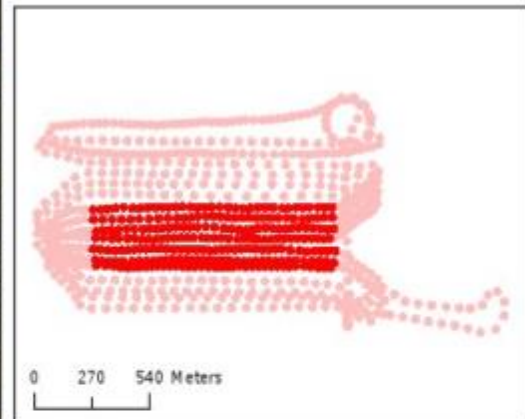
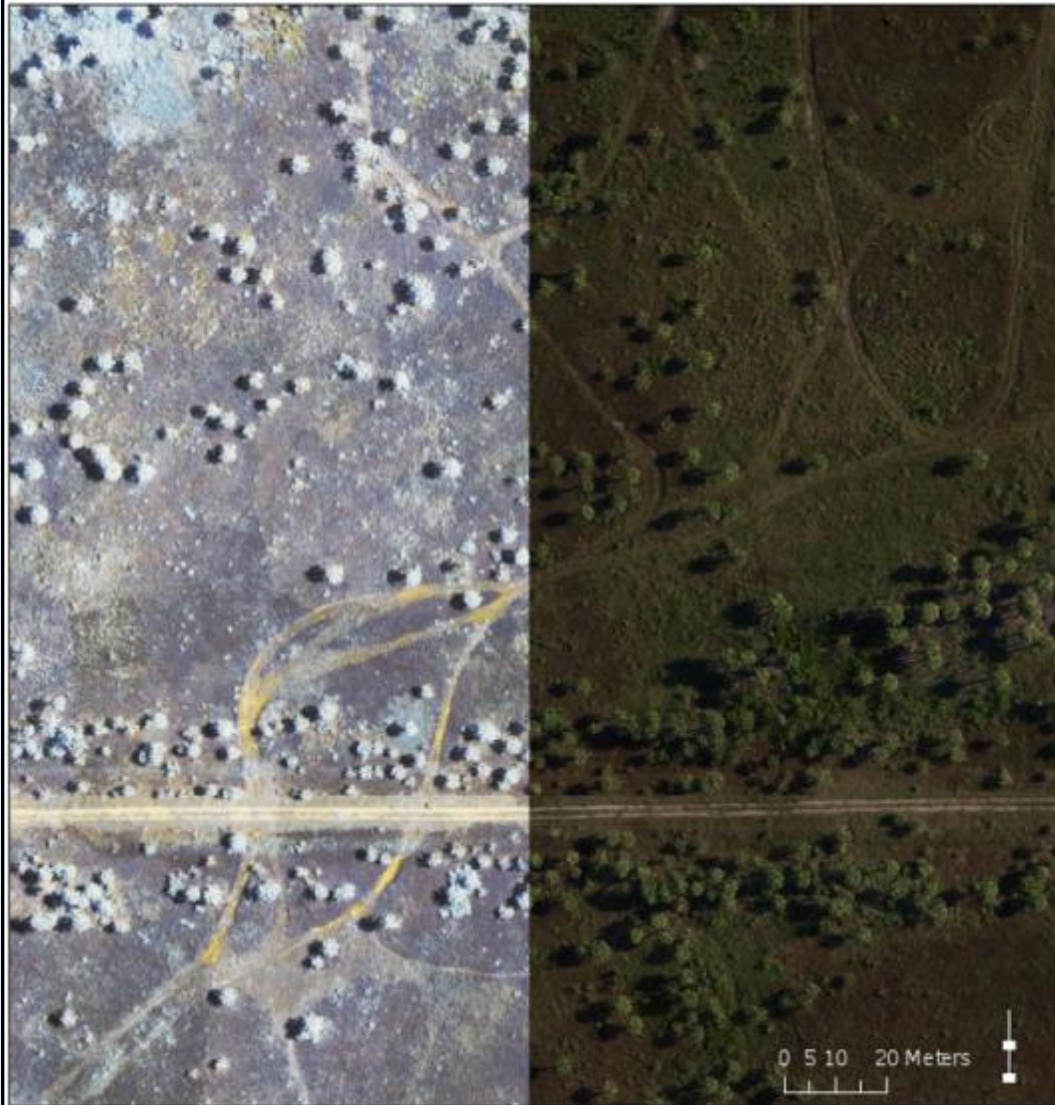
Acquired: July 7th, 2010 at 9:47 AM

Submitted: July 17th, 2010

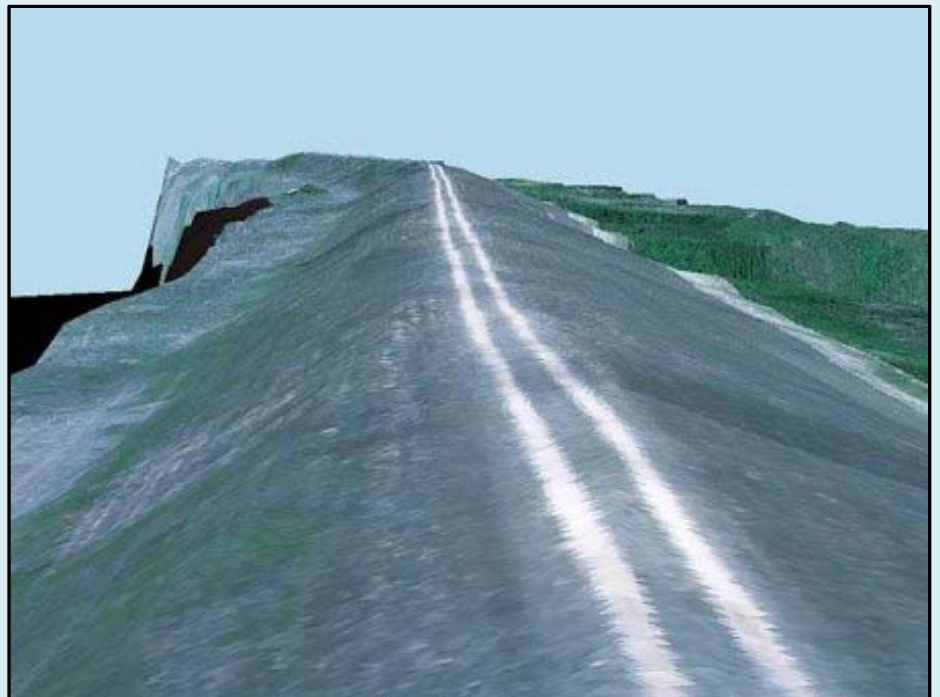
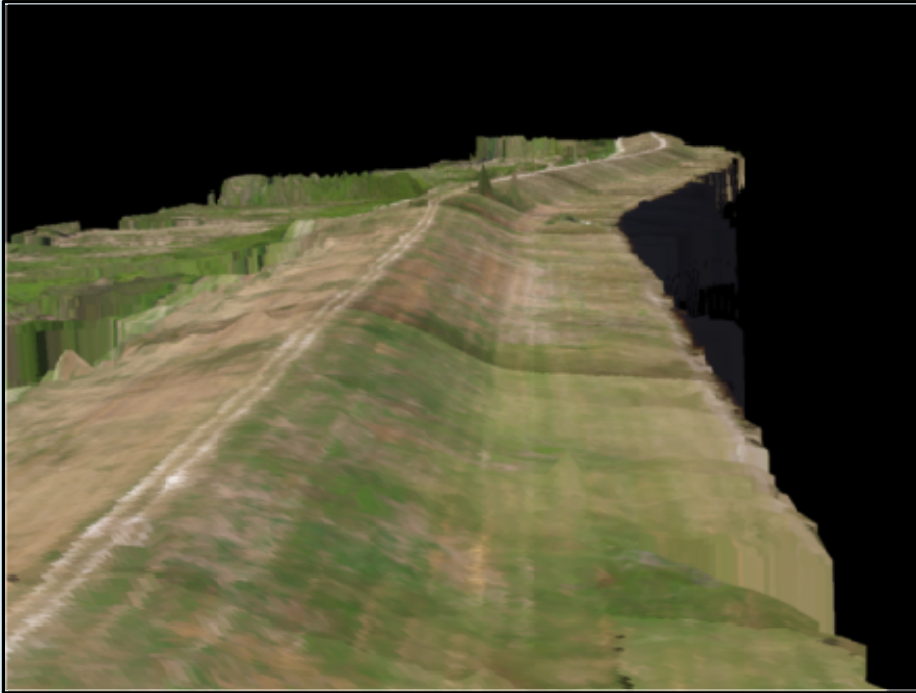
Description:

The 5 cm resolution color infrared (left) and 5 cm visible spectrum (right) orthomosaics are composed from two sets of directly georeferenced high resolution images. The U.S. Army Corp of Engineers, Jacksonville District, and the University of Florida Interdisciplinary UAV Research Group acquired this imagery using a hand-launchable autonomous aerial fixed-wing aircraft. The target area is being managed for invasive species.

The maps below show the location of each camera exposure from the visible imagery flight (top), highlighting the imagery that was included in the mosaic. Each flight was approximately 40 minutes in duration. The overview maps show the location of the target area relative to Picayune Strand State Forest (bottom-left) and Florida (bottom-right).



UFUASRP – 3-Dimensional Mosaics



UAS Technology is Now Prolific: Airspace Integration is Lagging



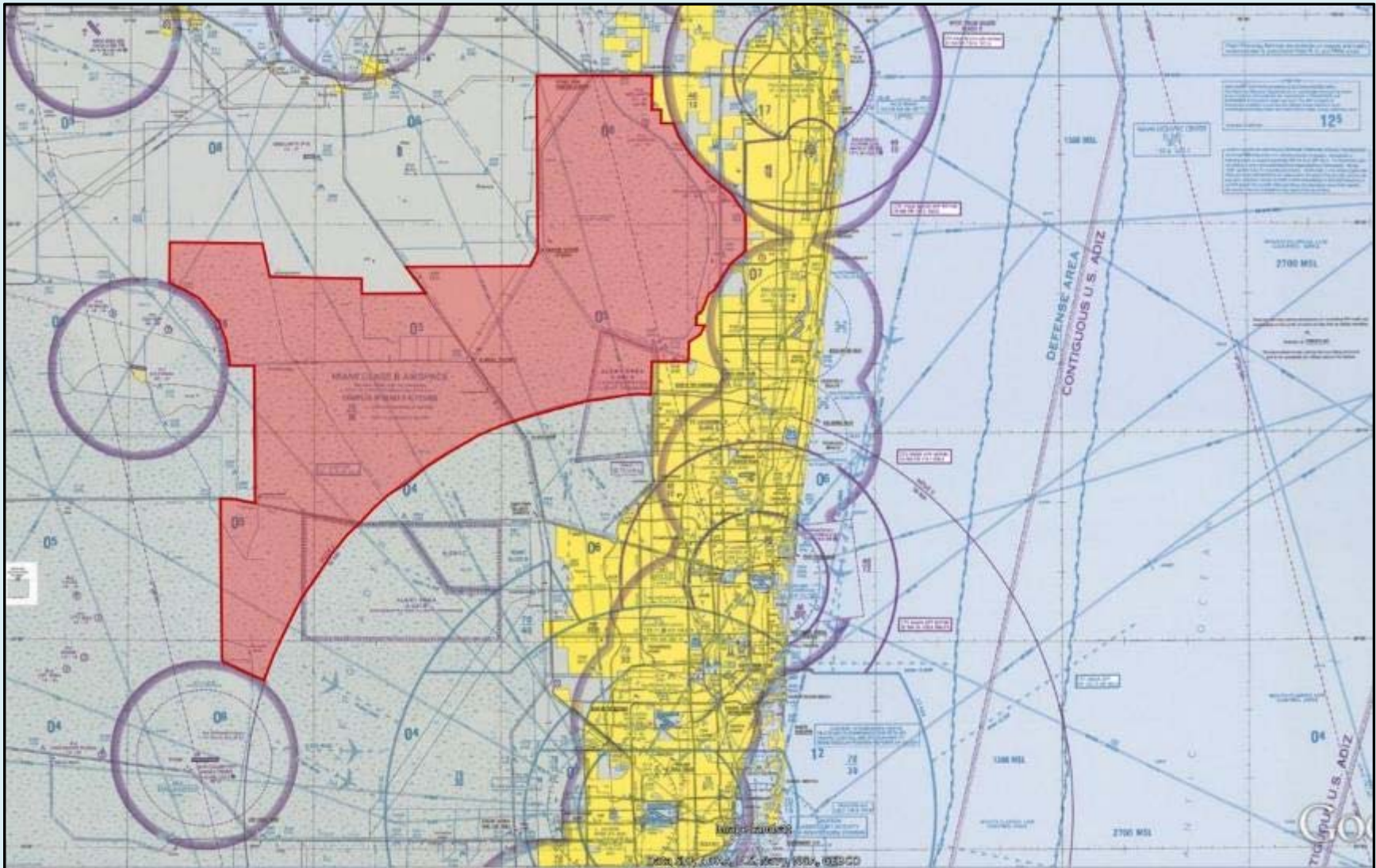
Be Patient...

Be Patient...

Be Patient...

Thinking About Using UAS as a Tool?

Gaining Airspace Permission Can be a Significant Limitation



Unmanned Aircraft Systems and their Sensors Have Potential to be a Great Tool for Natural Resource Users



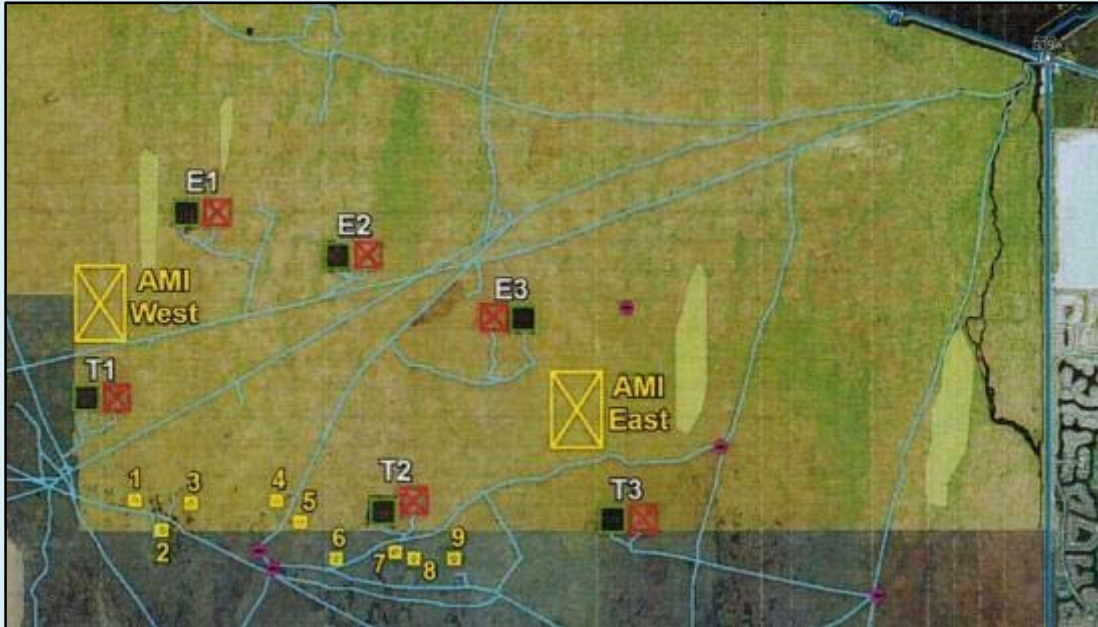
UFUASRP is Patient AND Adaptive...

Be Patient...



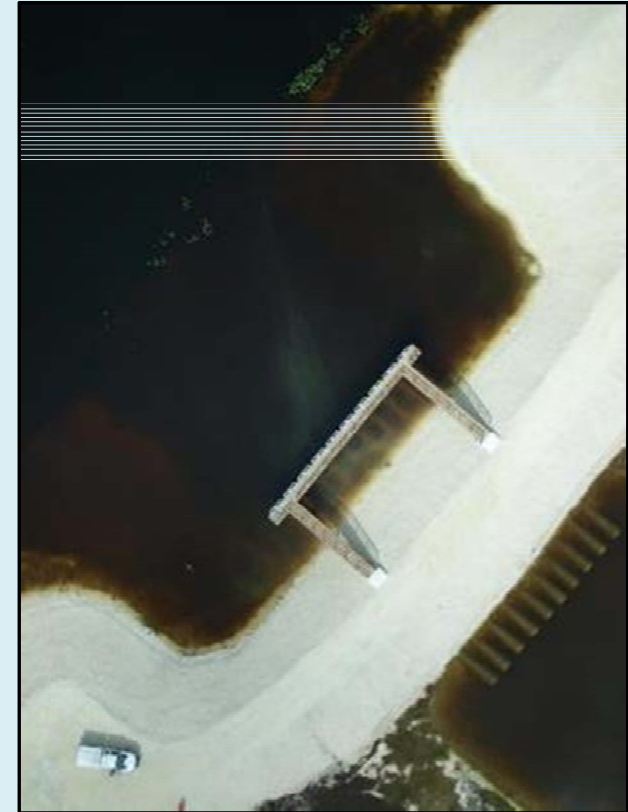
Active Restoration Project Monitoring

WCA-2



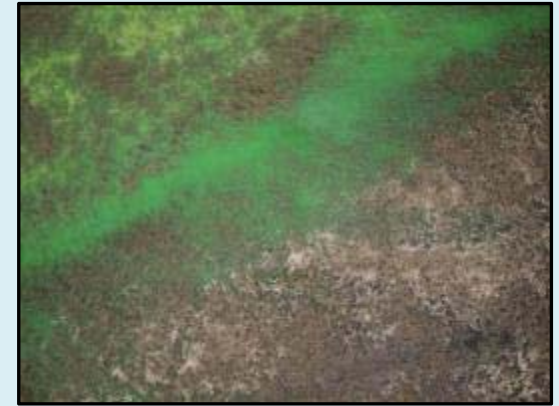
Active Restoration Project Monitoring

S-152 – L-67 Sheetflow Restoration

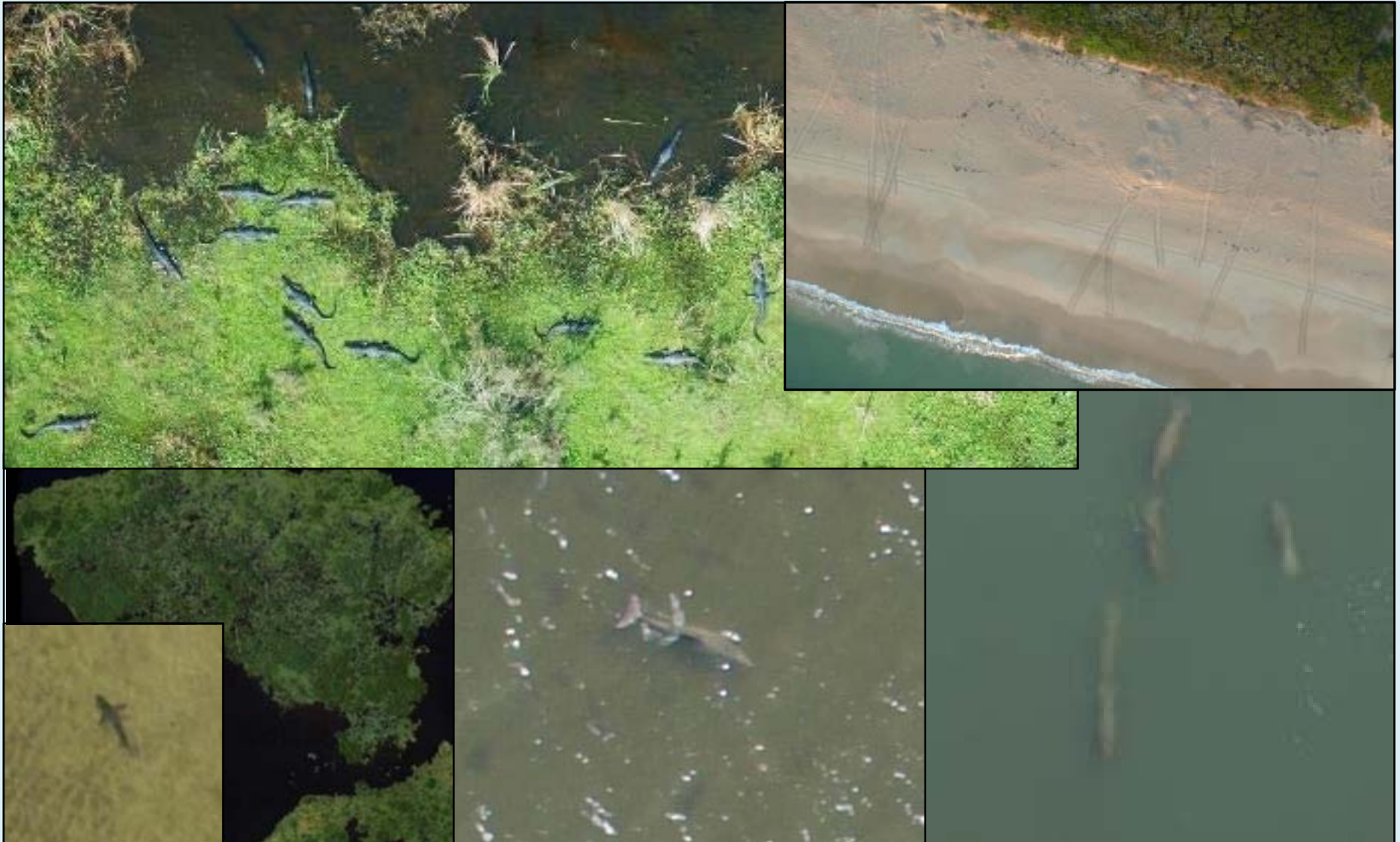


Active Restoration Project Monitoring

S-152 – L-67 Sheetflow Restoration



What is Your Target?



UF UAS Research Program



Dr. H. Franklin Percival, UF WEC/Program Director
Mr. Matthew A. Burgess, UF WEC/Program Coordinator
Dr. Raymond R. Carthy, UF WEC/Wildlife Lead
Mr. Joseph G. DiRodio, UF WEC/Chief Pilot
Dr. Peter C. Frederick, UF WEC/Avian Lead
Dr. Peter G. Ifju, UF Aerospace/Aerospace Lead
Mr. Travis J. Whitley, UF Aerospace/Airframe and Controls Specialist
Mr. Tyler S. Ward, UF Aerospace/Payload and Sensor Specialist
Dr. Amr H. Abd-Elrahman, UF Geomatics/GIS Lead
Dr. Bon A. Dewitt, UF Geomatics/Photogrammetry Lead
Ms. Tiziana W. Munene, UF Geomatics/Imagery Processing Specialist
Dr. Scot E. Smith, UF Geomatics/Remote Sensing Lead
Dr. Benjamin E. Wilkinson, UF Geomatics/Imagery Processing Lead
Mr. Yun Ye, UF Geomatics/Remote Sensing Specialist



Questions?

Matthew A. Burgess

mburgess@ufl.edu

Department of Wildlife Ecology and Conservation

Institute of Food and Agricultural Sciences – University of Florida

U.S.G.S. – Florida Cooperative Fish and Wildlife Research Unit

<http://uav.ifas.ufl.edu/>

